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High Reliability, Easy to Use, A Combination of Intelligence and Versatility for Ultimate Performance

Delta Electronics, a leading brand of drive technology, has officially launched the most cost-effective VFD-C2000 series, a classical field oriented control AC motor drive. With 4 good CP values (high efficiency, high performance, low cost of maintenance and long product life), customers are able to raise the competition and save cost at the same time.

Main Functions and Features

- Field oriented control with built-in PLC function
- Wide variety of applications
- Wide range of models to meet requirements
- Modular design for easy maintenance and many extensions
- High-speed communication interface with built-in CANopen and MODBUS communication (optional cards for PROFIBUS-DP, DeviceNet, MODBUS TCP and EtherNet/IP)
- Long-life design and life detection of important components
- Enhanced protections and adaptation to ambient conditions
- Complies with global safety standards, including CE, UL and cUL

Standard Models (IP20/NEMA1)

Power range: 230V 0.75~90kW, 460V 0.75~355kW

_																	
1	230V (kW)	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90
:	230V (HP)	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100	125
F	rame Size		1	۹.			В					I	D				F*
	460V (kW)	0.75	1.5	2.2	3.7	4.0	5.5	7.5	11	15	18.5	22	30	37	45	55	75
	460V (HP)	1	2	3	5	5	7.5	10	15	20	25	30	40	50	60	75	100
F	rame Size			,	۹.				В)	
	460V (kW)	90	110	132	160	185	220	280	315	355							
	460V (HP)	125	150	175	215	250	300	375	425	475							
F	rame Size	E	≣	F	*	G	; *		Н*								

*NOTE: Available in 2010 Q2





Leading the Future of Drive Technology

VFD-C series uses FOC control as the core technology to fulfil the demands of high starting torque, accurate speed and torque control. Suitable for many applications it offers PID adjustment, simple operation interface, flexible I/O extension, fieldbus modules, wide power range, complete protection, adaptation to harsh ambient conditions, long-life design, compliance with global safety standards (CE/UL/cUL), competitive market price, easy maintenance, low malfunction rate and self diagnosis.

High-performance Variable-frequency Technology

- 1. Control bandwidth up to 600Hz
- 2. Speed/torque/position control mode
- 3. Dual rating design (Normal duty/heavy duty)
- 4. Outstanding 4-quadrant torque control/limit
- 5. 2 in 1

(induction motor and synchronous motor)*

*NOTE: Available in 2010 Q1

Versatile Driving Controls

- 1. Built-in safe stop function
- 2. Built-in PLC function
- 3. Built-in brake unit
- 4. Support various network protocols
- 5. Synchronous position control



Modular Design 1. Hot-plugging digital

- keypad
- 2. I/O extension cards
- 3. Various PG (encoder) feedback cards
- 4. Network cards for fieldbus modules
- 5. Removable fan

Environmental Adaptability

- 1. 50°C operation temperature
- 2. Built-in DC reactor
- 3. Coated circuit boards
- 4. RFI filter
- 5. Global safety standards (CE/UL/cUL)

Enhanced Motor Efficiency in General Applications

■ Improved sensorless vector control (SVC) response and torque control in, for example, crane applications.



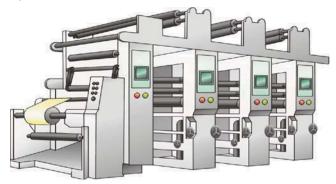
Safe Stop Function

■ VFD-C2000 series complies with safe stop standards, including EN954-1, EN60204-1 and IEC61508, to prevent personal injury from accidental start-up.



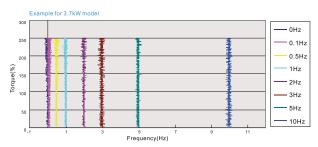
High-performance Field Oriented Control

■ The best choice for high precision control of position and speed, such as the control of printing machines.



High-performance Field Oriented Control

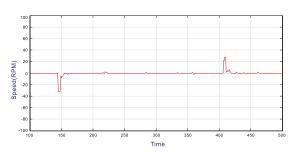
■ In FOC+PG control mode it can produce 200% start-up torque at extremely low speeds, resulting in more stable speed control.



Improved Load Impact

■ At load changes, VFD-C2000 will provide the best torque response by FOC to reduce motor speed changes to a minimum to prevent vibration.





Innovative PID Technology

■ Apart from traditional PI control, VFD-C2000 also provides PDFF control in speed regulation to eliminate overshoot and increase response time.



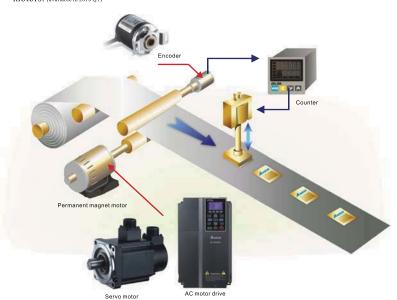
Intelligent Programmable Logical Controller

■ In network systems, distributed control and independent operation can easily be achieved with the built-in Delta PLC.



Able to Drive Permanent Magnet(PM) Motor

■ VFD-C2000 series offers 2-in-1 function for induction motors and permanent magnet motors to precisely control position, speed and torque by dynamic response of permanent magnet motors. (available in 2010 01)

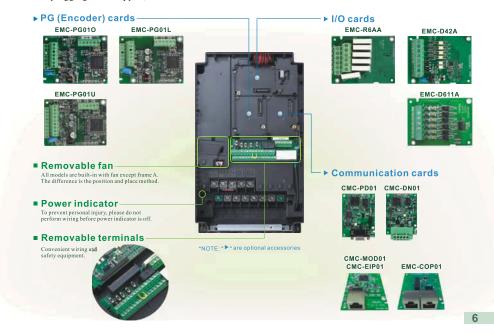


Modular Design

■ The modular design fulfils the needs of system applications and equipment maintenance.



Provides various accessories, including I/O extension cards, encoder feedback cards, communication cards, hot-plugging LCM keypad, removable terminals and removable fan.



High-speed Network Building

- Provides various communication network cards and fieldbus cards
- Built-in RS-485 international standard communication interface
- Advanced network functions



■ CANO⊘⊘∩ (DS402), built-in

Delta develops the software CANopen Builder exclusively designed for CANopen communication. It provides users with a more convenient interface for motion control and greatly increases productivity.

- Supports all Delta industrial automation products (all EDS files of Delta industrial automation products are built-in)
- I/O data layout of each equipment on the CANopen network
- · Planning function for motion control

 TAP-CN03 distribution box for long distances







Delta DeviceNet Builder software is particularly designed for DeviceNet communication.

With this software, it is easy to plan DeviceNet equipment and remote I/O via parameters to build a standard DeviceNet monitoring structure.

- DeviceNet layout software
- Supports all Delta industrial automation products (all EDS files of Delta industrial automation products are built-in)
- . I/O data layout of each equipment in DeviceNet network





■ MODBUSTCP

Delta's communication integrator software not only provides graphic module setting and human interface design but also supports settings and online monitoring for all Ethernet products



- Delta software for Ethernet/MODBUS TCP products
- · Graphic module setting and human interface design Setting interface for virtual COM port

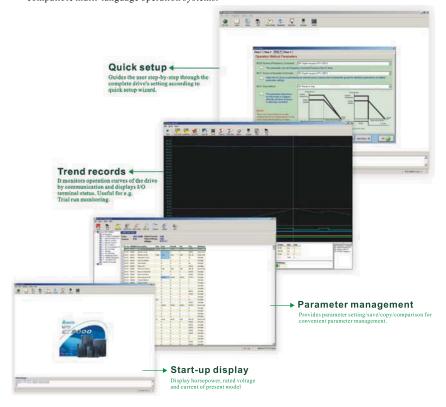
Environmental Adaptability Design

- Those models which have built-in with DC reactor and RFI filter comply with IEC/EN61000-3-2, 61000-3-12 and 61800-3 standards.
- Reduces harmonics and noise interference effectively
- Strong coating to ensure safe operation in harsh environments
- Heatsink and electronics components are completely isolated from each other. With the following two heatsink designs, the best cooling according to requirements is achieved:
- (1) Flange mounting: Heat from the drive can be dissipated out of the cabinet
- (2) Forced fan cooling: Blow cool air into aluminum heatsink.



Convenient Operation Platform for Drive System Management

■ Provides a complete operation platform for users' easy control and monitoring via PC, including parameters save/setting, real-time wave monitor, quick setup, support multiple languages and compatible multi-language operation systems.

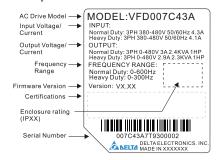


Ordering information

Frame A	230V: 0.75~3.7kW (1~5HP) 460V: 0.75~5.5kW (1~7.5HP)	VFD007C23A/E VFD037C23A/E VFD007C43A/E VFD015C43A/E VFD037C43A/E VFD040C43A/E VFD055C43A/E VFD015C23A/E	► Flange mounting kit 「MKC-AFM」 ► Flange mounting kit
		VFD022C23A/E VFD022C43A/E	[MKC-AFM1]
Frame B	230V: 5.5~11kW (7.5~15HP) 460V: 7.5~15 kW (10~20HP)	VFD055C23A/E VFD075C23A/E VFD110C23A/E VFD075C43A/E VFD110C43A/E VFD150C43A/E	▶ Flange mounting kit 「MKC-BFM」
Frame C	230V: 15~22 kW (20~30HP) 460V: 18.5~30 kW (25~40HP)	VFD150C23A/E VFD185C23A/E VFD220C23A/E VFD185C43A/E VFD220C43A/E VFD300C43A/E	► Flange mounting kit 「MKC-CFM」
Frame D	230V: 30~37 kW (40~50HP) 460V: 37~75 kW (50~100HP)	VFD300C23A VFD370C23A VFD370C43A VFD450C43A VFD550C43A VFD750C43A VFD300C23E VFD370C23E VFD370C43E VFD450C43E VFD550C43E VFD750C43E	► Conduit box kit 「MKC-DN1CB」
Frame E	230V: 45-55 kW (60~75HP) 460V: 90~110 kW (125~150HP)	VFD450C23A/E VFD550C23A/E VFD900C43A/E VFD1100C43A/E VFD750C23E	► Conduit box kit 「MKC-EN1CB」
Frame F	230V: 75-90 kW (100~125HP) 460V: 132~160 kW (175~215HP)	VFD750C23A VFD900C23A/E VFD1320C43A/E VFD1600C43A/E	available in 2010 Q2
Frame G	460V: 185~220 kW (250~300HP)	VFD1850C43A/E VFD2200C43A/E	available in 2010 Q2
Frame H	460V: 280~355 kW (375~475HP)	VFD2800C43A/E VFD3150C43A/E VFD3550C43A/E	available in 2010 Q2
			NOTE: " h " are optional accessories

*NOTE: *> " are optional accessories

■ Nameplate



■ Model name VFD 007 C 43 A Version type Input voltage 23:230V 3-Phase 43:460V 3-Phase C2000 series Applicable motor power in kW 007:1HP(0.75kW)~1100:150HP(110kW) Refer to the specifications for details

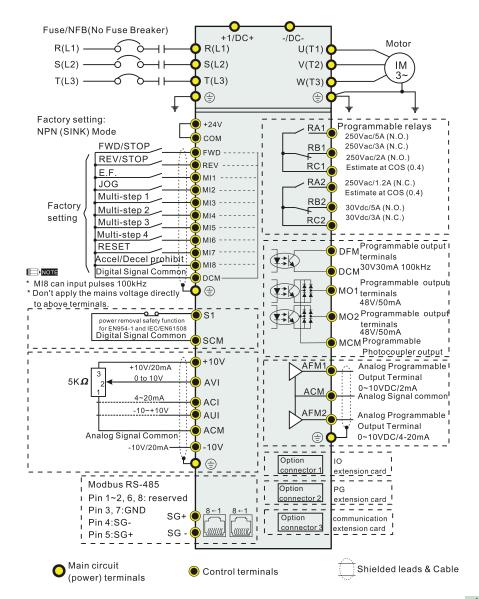
Series name(Variable Frequency Drive)

■ Optional Accessories

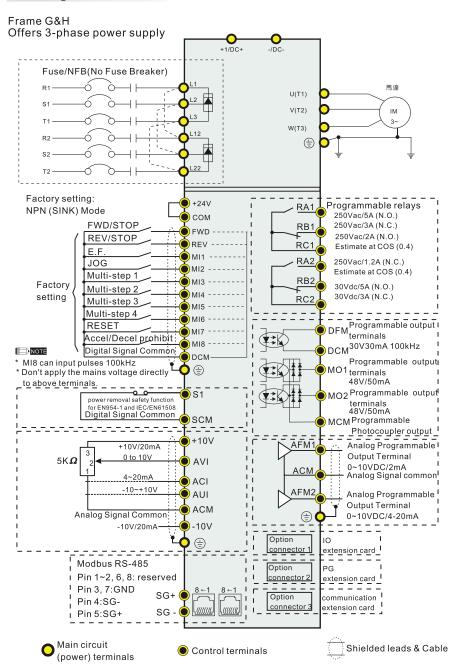
	CMC-EIP01 CMC-MOD01	EtherNet/IP (CMC-EIP01) MODBUS TCP (CMC-MOD01) 10/100 Mbps Auto-Detect
Communication	CMC-PD01	PROFIBUS-DP Supports 9.6kbps, 19.2kbps, 96.75kbps, 187.5kbps, 500kbps, 1.5Mbps, 3Mbps, 6Mbps and 12Mbps
card	CMC-DN01	DeviceNet 125kbps, 250kbps, 500kbps and extenable serial transmission speed
	CMC-COP01	CANopen 1M 500k 250k 125k 100k 50k
Converter	1F2 6530	USB-Lo-RS-485 converter Provides 9V power supply for VFD-C2000 keypad (KPC-CC01) to save parameters and edit pages Communication speed up to 1,152kbps No need to have external power supply and auto-detect the direction of data flow USB plug-and-elyst function
	EMC-R6AA	Relay card (6 relays)
I/O card	EMC-D42A	I/O extension card (4 digital inputs and 2 digital outputs)
	EMC-D611A	Input extension card (6 inputs)
	EMC-PG010	PG output signal with frequency division function: Open collector output signal. It requires a pull-up resistor to external power V+ (such as PLC power) to prevent noise interference. Max. output frequency: 300kPulse/Sec
PG (encoder)	EMC-PG01L	PG output signal with frequency division function (1-255 times) Max. output voltage of line driver: SVDC Max. output current: 50mA Max. output frequency: 300kPulse/Sec Open collector output signal and needs to add a pull-up resistor to prevent noise interference.
card	EMC-PG01U	PG output signal with frequency division function (1-255 times) Max. output vollage of line driver: 5VDC Max. output current: 50mA Max. output frequency: 300NPulse/Sec Two modes: 1. standard UVW output encoder, 2. Delta wiring-saving encoder (ABZ)
	EMC-PG01R	PG output signal with frequency division function (1-255 times) Max. output voltage of line driver: 5VDC Max. output current: 50MA Max. output frequency: 300kPulse/Sec
Digital keypad	KPC-CE01	7-segment display with menu function:easy, convenient operation, multi-function keys, warning indicators and fault code display Panel mounting (MKC-KPPK) IP56 protection level, can be mounted flat on the surface of a cabinet and the front cover is waterproof. Two ways of panel mounting: wall mounting
	0.80	and embedded mounting. Customers are able to install as required.

Frame A~C Offers 3-phase power supply DC choke Brake resistor (optional) Jumper (0000) (optional) Fuse/NFB(No Fuse Breaker) +2 +1 B1 B2 Motor R(L1) R(L1) U(T1) S(L2) S(L2) V(T2) IM T(L3) T(L3) W(T3) (1) (1) Factory setting: +24V RA1 Programmable relays NPN (SINK) Mode 250Vac/5A (N.O.) COM FWD/STOP 250Vac/3A (N.C.) RB1 250Vac/2A (N.O.) REV/STOP RC1 Estimate at COS (0.4) E.F. RA2 250Vac/1.2A (N.C.) JOG Estimate at COS (0.4) Multi-step 1 RB2 Factory 30Vdc/5A (N.O.) Multi-step 2 setting 30Vdc/3A (N.C.) RC2 Multi-step 3 Multi-step 4 DFM Programmable output I TRESET terminals Accel/Decel prohibit DCM^{30V30mA} 100kHz Digital Signal Common NOTE Programmable outputs * MI8 can input pulses 100kHz MO1_{terminals} * Don't apply the mains voltage directly 48V/50mA to above terminals. MO2 Programmable output power removal safety function)S1 terminals 48V/50mA for EN954-1 and IEC/EN61508 Digital Signal Common MCM Programmable SCM Photocoupler output ĀĒMĪ, Analog Programmable +10V/20mA **Output Terminal** 0 to 10V $5K\Omega$ 0~10VDC/2mA ACM Analog Signal common 4~20mA) ACI -10~+10V AFM2) AUI Analog Programmable Output Terminal Analog Signal Common 0~10VDC/4-20mA -10V/20mAextension card I Modbus RS-485 Option ı Pin 1~2, 6, 8: reserved connector 2 extension card ¹ Pin 3, 7:GND Option Pin 4:SGconnector 3 extension card i Pin 5:SG+ Main circuit Shielded leads & Cable Control terminals (power) terminals

Frame D and above Offers 3-phase power supply



Wiring



Specifications

230	w	Frame Size		,	4			В			С		[)		Е		F
		Model Number VFDC	007	015	022	037	055	075	110	150	185	220	300	370	450	550	750	900
		Max. Applicable Motor Output (kW)	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90
		Max. Applicable Motor Output (hp)	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100	125
5	HEAVY DUTY	Rated Output Capacity (kVA)	1.9	2.8	4.0	6.4	9.6	12	19	25	28	34	45	55	68	81	96	131
Rating	¥	Rated Output Current (A)	4.8	7.1	10	16	24	31	47	62	71	86	114	139	171	204	242	329
Ra	뽀	Carrier Frequency (kHz)			2	~15kH	z				2	~10kH	z			2~	9kHz	
Output	NORMAL DUTY	Rated Output Capacity (kVA)	2.0	3.2	4.4	6.8	10	13	20	26	30	36	48	58	72	86	102	138
0	RMA	Rated Output Current (A)	5	8	11	17	25	33	49	65	75	90	120	146	180	215	255	346
	2	Carrier Frequency (kHz)			2	~15kH	z				2	~10kH	z			2~9	kHz	
g		Input Current (A) Heavy Duty	6.1	11	15	18.5	26	34	50	68	78	95	118	136	162	196	233	315
Rating		Input Current (A) Normal Duty	6.4	12	16	20	28	36	52	72	83	99	124	143	171	206	245	331
Input		Rated Voltage/Frequency					3-ph	aseAC	200V	~240V	(-15%	~+10%	6),50/	60Hz				
드		Operating Voltage Range								170~2	65Vac							
		Frequency Tolerance								47~	63Hz							
		Cooling Method	Natural							Fanc	ooling							
		Braking Chopper					Built	-in							Op	tion		
		DC Reactor					Option						Built-in					
		EMI Filter					Option											

eneral Specification	ons
Control Method	1: V/F, 2: SVC, 3: VF+PG, 4: FOC+PG
Starting Torque	up to 150% or above at 0.5Hz; up to 150% at 0Hz for 1 minute
V/f Curve	4-point adjustable V/f curve & square curve
Speed Response Bandwidth	5Hz (vector control can be up to 40Hz)
Torque Limit	Max. 200% torque current
Torque Accuracy	±5%
Max. Output Frequency (Hz)	Normal duty:0.01~600.00Hz; Heavy duty: 0.00 ~ 300.00 Hz
Frequency Output Accuracy	Digital command: ±0.01%, -10° ~+40°, Analog command: ±0.1%, 25 ±10° €
Frequency Setting Resolution	Digital command: 0.01Hz, Analog command: 0.03/60 Hz (±11 bits)
Max. Output Frequency (Hz) Frequency Output Accuracy Frequency Setting Resolution Overload Tolerance	Normal duty: 120% of rated output current for 1 min. Heavy duty: 150% of rated output current for 1 min.
Frequency Setting Signal	+10V~-10,0~+10V,4~20mA,0~20mA,Pulse input
Accel./decel. Time	0.00~600.00/0.0~6000.0 Seconds
Main Control Function	Torque control, Speed/torque control switching, Feed forward control, Zero-servo control, Momentary power loss ridethru, Speed search, Over-torque detection, Torque limit, 16-step speed (including master speed), Accel/decel time switch, S-curve accel/dece 3-wire sequence, Auto-Tuning (rotational, stationary), Dwell, Slip compensation, Torque compensation, Skip frequency, Frequency upper/lower limit settings, DC injection braking at start/stop, High slip braking, PID control (with sleep function), Energy saving control, MODBUS communication (RS-485 RJ46) max. 115.2 kbps), Fault restart and Parameter copy
Fan Control	Frame B and below: ON/OFF switch; frame C and above: PWM control
Motor Protection	Electronic thermal relay protection
Over-current Protection	The current forces 240% of the over-current protection Current clamp: normal duty: 170~175%; heavy duty: 180~185%
Over-voltage Protection	230: drive will stop when DC-BUS voltage exceeds 410V 460: drive will stop when DC-BUS voltage exceeds 820V
Over-current Protection Over-voltage Protection Over-temperature Protection Stall Prevention Re-start after Momentary Power Off	Built-intemperaturesensor
Stall Prevention	Stall prevention during acceleration, deceleration and running independently.
Re-start after Momentary Power Off	Parameter setting can be up to 20 seconds
Ground Current Protection	Ground current protection level is 50% of rated current of the AC motor drive

Specifications

		Frame Size				Ą				В	В		С	
46	ov)		007	0.4.5	022	037	040	055	075		150	405		0.00
		Model Number VFDC	007	015	022	037	040	055	075	110	150	185	220	300
		Max. Applicable Motor Output (kW)	0.75	1.5	2.2	3.7	4.0	5.5	7.5	11	15	18.5	22	30
		Max. Applicable Motor Output (hp)	1	2	3	5	5	7.5	10	15	20	25	30	40
5	HEAVY DUTY	Rated Output Capacity (kVA)	2.3	3.0	4.5	6.5	7.6	9.6	14	18	24	29	34	45
Rating	I ≨	Rated Output Current (A)	2.9	3.8	5.7	8.1	9.5	11	17	23	30	36	43	57
Ra		Carrier Frequency (kHz)				2	~15kH	z				2	~10kH	z
Output	NORMAL DUTY	Rated Output Capacity (kVA)	2.4	3.2	4.8	7.2	8.4	10	14	19	25	30	36	48
0	SMA.	Rated Output Current (A)	3.0	4.0	6.0	9.0	10.5	12	18	24	32	38	45	60
	Š	Carrier Frequency (kHz)	2~15kHz 2~10kHz											z
Ę.		Input Current (A) Heavy Duty	4.1	5.6	8.3	13	14.5	16	19	25	33	38	45	60
Input Rating		Input Current (A) Normal Duty	4.3	5.9	8.7	14	15.5	17	20	26	35	40	47	63
D III		Rated Voltage/Frequency			3-ph	aseAC	380V	~480V	(-15%	~+109	6),50/	60Hz		
드		Operating Voltage Range						323~5	28Vac					
		Frequency Tolerance						47~0	33Hz					
		Cooling Method	Nat	ural					Fanc	ooling				
		Braking Chopper						Bui	lt-in					
		DC Reactor						Ор	tion					
		EMI Filter	VFDXXXC43A: without EMI filter VFDXXXC43E: built-in EMI filter											

46	ov	Frame Size		Į.			E		*	F	*	G		*H	
40	"	Model Number VFDC	370	450	550	750	900	1100	1320	1600	1850	2200	2800	3150	3550
		Max. Applicable Motor Output (kW)	37	45	55	75	90	110	132	160	185	220	280	315	355
		Max. Applicable Motor Output (hp)	50	60	75	100	125	150	175	215	250	300	375	425	475
0	HEAVY DUTY	Rated Output Capacity (kVA)	55	69	84	114	136	167	197	235	280	348	417	466	517
ij	₹	Rated Output Current (A)	69	86	105	143	171	209	247	295	352	437	523	585	649
8	뿐	Carrier Frequency (kHz)		2~1	OkHz					2	2~9kH:	z			
Output Rating	NORMAL DUTY	Rated Output Capacity (kVA)	58	73	88	120	143	175	207	247	295	367	438	491	544
0	RMA	Rated Output Current (A)	73	91	110	150	180	220	260	310	370	460	550	616	683
	S S	Carrier Frequency (kHz)		2~1	OkHz					2	2~9kH:	z			
9	,	Input Current (A) Heavy Duty	70	96	108	149	159	197	228	285	361	380	469	527	594
Input Rating		Input Current (A) Normal Duty	74	101	114	157	167	207	240	300	380	400	494	555	625
ing		Rated Voltage/Frequency			3-ph	aseAC	380V	~480V	(-15%	~+10%	6),50/	60Hz			
=		Operating Voltage Range							3~528						
		Frequency Tolerance							7~63H	_					
		Cooling Method							n cool	U					
		Braking Chopper							Optior						
		DC Reactor							Built-ir	1					
		EMI Filter	VFDXXXC43A: without EMI filter VFDXXXC43E: conduit box kit; VFDXXX43E: NEMA1 built-in FMI filter												

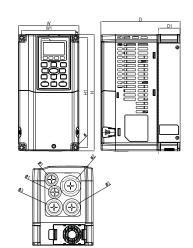
Ge	neral Specificatio	ns
	Control Method	1: V/F, 2: SVC, 3: VF+PG, 4: FOC+PG
	Starting Torque	up to 150% or above at 0.5Hz; up to 150% at 0Hz for 1 minute
	V/f Curve	4-point adjustable V/f curve & square curve
	Speed Response Bandwidth	5Hz (vector control can be up to 40Hz)
	Torque Limit	Max. 200% torque current
	Torque Accuracy	±5%
Control Characteristics	Max. Output Frequency (Hz)	Normal duty: 0.01~600.00Hz; Heavy duty: 0.00~300.00 Hz
racter	Frequency Output Accuracy	Digital command: ±0.01%, -10°C ~+40°C, Analog command: ±0.1%, 25 ±10°C
Cha	Frequency Setting Resolution	Digital command: 0.01Hz, Analog command: 0.03/60 Hz (±11 bits)
Sontro	Overload Tolerance	Normal duty: 120% of rated output current for 1 min. Heavy duty: 150% of rated output current for 1 min.
٦l	Frequency Setting Signal	+10V~-10,0~+10V,4~20mA,0~20mA,Pulse input
	Accel./decel. Time	0.00~600.00/0.0~6000.0 Seconds
	Main Control Function	Torque control, Speed/torque control switching, Feed forward control, Zero-servo control, Momentary power loss ridethru, Speed search, Over-torque detection, Torque limit, 16-step speed (including master speed), Accel/decel time switch, S-curve accel/decel, 3-wire sequence, Auto-Tuning (rotational, stationary), Dwell, Slip compensation, Torque compensation, Skip frequency, Frequency upper/lower limit settings, DC injection braking at start/stop, High slip braking, PID control (with sleep function), Energy saving control, MODBUS communication (RS-485 RJ45) max. 115.2 kbps), Fault restart and Parameter copy
	Fan Control	Frame B and below: ON/OFF switch; frame C and above: PWM control
	Motor Protection	Electronic thermal relay protection
stics	Over-current Protection	The current forces 240% of the over-current protection Current clamp: normal duty: 170~175%; heavy duty: 180~185%
acteris	Over-voltage Protection	230: drive will stop when DC-BUS voltage exceeds 410V 460: drive will stop when DC-BUS voltage exceeds 820V
Protection Characteristics	Over-temperature Protection	Built-in temperature sensor
<u></u>	Stall Prevention	$Stall\ prevention\ during\ acceleration,\ deceleration\ and\ running\ independently.$
rotect	Re-start after Momentary Power Off	Parameter setting can be up to 20 seconds
٦	Ground Current Protection	Ground current protection level is 50% of rated current of the AC motor drive

Environment for Operation, Storage and Transportation

П	Installation location	IEC60364-1/	EC60664-1 Pollution de	gree 2,Indoor use only				
ı		Operation	NEMA 1/UL Type 1	When operating at rated current, the surrounding temperature must be within -10 -+ 40 °C.For 40 °C-60 °C, please derate 2% rated current per increasing 1 °C.				
ı	Surrounding Temperature	Operation	UL Open Type	When operating at rated current, the surrounding temperature must be within -10 -+ 50 $^{\circ}$ C. For 50 $^{\circ}$ C-60 $^{\circ}$ C, please derate 2% rated current per increasing 1 $^{\circ}$ C.				
		Storage/ Tra	nsportation	-25°C ~ +70°C				
		No condens	ation, no frost					
		Operation		Max. 90%				
	Rated Humidity	Storage/ Tra	nsportation	Max. 95%				
Environment		No condens	ation					
ē	Air Pressure	Operation/ S		86 to 106 kPa				
		Transportati		70 to 106 kPa				
ĕ∥			3 (application is in progre	,				
έl		Operation		Class 3C2 : Class 3S2				
Ш	Pollution Level	Storage		Class 2C2 : Class 2S2				
ı		Transportati	ion	Class 1C2 : Class 1S2				
п		No condens	ation					
ı	Altitude	Operation		n, please derate 2% rated current or decrease 0.5°C surrounding e corner grounded system can only be used at 2000m and below.				
п	Package Drop	Storage/ Tra	nsportation	ISTA procedure 1A(according to weight) IEC60068-2-31				
	Vibration	1.0mm peak t	o peak, 2-13.2Hz. 0.7-1.	0G: 13.2-55Hz; 1.0G: 55-512Hz (comply with IEC 60068-2-6				
	Shock Resistance	Comply with I	EC/EN 60068-2-27					
	Operation Position		offset angle ±10°	10 [*] →₩ ⁻⁴ -10*				

Dimensions

Frame A



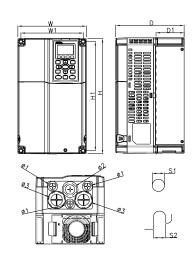
MODEL

VFD007C23A/23E VFD007C43A/43E VFD015C23A/23E VFD015C43A/43E VFD022C23A/23E VFD022C43A/43E VFD037C23A/23E VFD037C43A/43E VFD040C43A/43E VFD055C43A/43E

Unit : mm[inch]

F	rame	W	Н	D	W1	H1	D1*	Ø	Ø1	Ø2	Ø3
A1	mm	130.0	250.0	170.0	116.0	236.0	45.8	6.2	22.2	34.0	28.0
AI	inch	5.12	9.84	6.69	4.57	9.29	1.80	0.24	0.87	1.34	1.10

■ Frame B



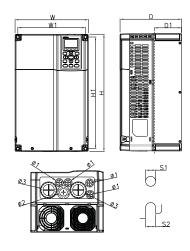
MODEL

VFD055C23A/23E VFD055C23A/23E VFD075C23A/23E VFD075C43A/43E VFD110C23A/23E VFD110C43A/43E VFD150C43A/43E

Unit : mm[inch]

F	rame	W	Н	D	W1	H1	D1*	S1	S2	Ø1	Ø2	Ø3
В1	mm	190.0	320.0	190.0	173.0	303.0	77.9	8.5	8.5	22.2	34.0	43.8
ъ1	inch	7.48	12.60	7.48	6.81	11.93	3.07	0.33	0.33	0.87	1.34	1.72

Frame C



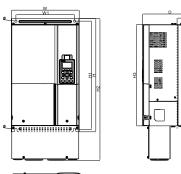
MODEL

VFD150C23A/23E VFD185C23A/23E VFD185C23A/23E VFD185C43A/43E VFD220C23A/23E VFD220C43A/43E VFD300C43A/43E

Unit : mm[inch]

F	rame	W	Н	D	W1	H1	D1*	S1	S2	Ø1	Ø2	Ø3
C4	mm	250.0	400.0	210.0	231.0	381.0	92.9	8.5	8.5	22.2	34.0	50.0
Ci	inch	9.84	15.75	8.27	9.09	15.00	3.66	0.33	0.33	0.87	1.34	1.97

Frame D



MODEL

FRAME D1	FRAME_D2
VFD300C23A	VFD300C23E
VFD370C23A	VFD370C23E
VFD370C43A	VFD370C43E
VFD450C43A	VFD450C43E
VFD550C43A	VFD550C43E
VFD750C43A	VFD750C43E



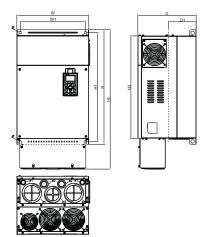
Unit : mm[inch]

Frame	W	Н	D	W1	H1	H2	Н3	D1*	Ø	Ø1	Ø2	Ø3
D1	330.0 [12.99]	550.0 [21.65]	275.0 [10.83]	285.0 [11.22]	525.0 [20.67]	-	492.0 [19.37]	107.2 [4.22]	11.0 [0.43]	34.0 [1.34]	22.0 [0.87]	11.0 [0.43]
D2	330.0 [12.99]	550.0 [21.65]	275.0 [10.83]	285.0 [11.22]	525.0 [20.67]	688.3 [27.10]	492.0 [19.37]	107.2 [4.22]	11.0 [0.43]	34.0 [1.34]	22.0 [0.87]	11.0 [0.43]

18 ▶

Dimensions

■ Frame E



MODEL

FRAME_E1 FRAME_E2 VFD450C23E VFD450C23A VFD550C23A VFD900C43A VFD1100C43A

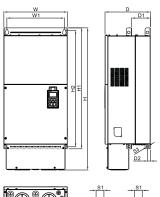
VFD550C23E VFD900C43E VFD1100C43E

Unit : mm[inch]

Frame	W	Н	D	W1	H1	H2	Н3	D1*	Ø	Ø1	Ø2	Ø3	Ø4
E1	370.0 [14.57]	589.0 [23.19]	300.0 [11.81]	335.0 [13.19]	560.0 [22.05]	-	528.0 [20.80]		13.0 [0.51]				
E2	370.0 [14.57]	589.0 [23.19]	300.0 [11.81]	335.0 [13.19]	560.0 [22.05]	715.8 [28.18]	528.0 [20.80]	143.0 [5.63]	13.0 [0.51]	22.0 [0.87]	34.0 [1.34]	76.0 [2.99]	92.0 [3.62]

D1* : Flange mounting

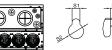
Frame F



MODEL

FRAME_F1 VFD900C23A VFD1320C23A VFD1600C23A

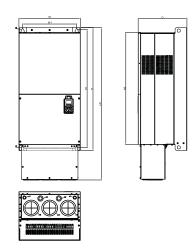
FRAME_F2 VFD900C23E VFD1320C43E VFD1600C43E



Unit : mm[inch]

Frame	W	Н	D	W1	H1	H2	D1	D2	S1	S2	S3
F1	420.0 [16.54]	-	300.0 [11.81]	380.0 [14.96]	800.0 [31.50]	770.0 [30.32]	124.0 [4.88]	18.0 [0.71]	13.0 [0.51]	25.0 [0.98]	18.0 [0.71]
F2	420.0 [16.54]	940.0 [37.00]	300.0 [11.81]	380.0 [14.96]	800.0 [31.50]	770.0 [30.32]	124.0 [4.88]	18.0 [0.71]	13.0 [0.51]	25.0 [0.98]	18.0 [0.71]

Frame G



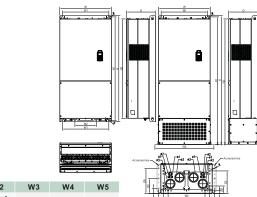
MODEL

FRAME_G1 VFD1850C43A VFD2200C43A FRAME_G2 VFD1850C43E VFD2200C43E

Unit : mm[inch]

Frame	W	Н	D	W1	H1	H2	Н3	Ø	Ø1	Ø2	Ø3
G1	550.0 [19.69]	1000.0 [39.37]	397 [15.63]	440.0 [217.32]	963.0 [37.91]	-	913.6 [35.97]	13.0 [0.51]	-	-	-
G2	550.0 [19.69]	1000.0 [39.37]	397 [15.63]	440.0 [217.32]	963.0 [37.91]	1240.2 [48.83]	913.6 [35.97]	13.0 [0.51]	22.0 [0.87]	34.0 [1.34]	117.5 [4.63]

■ FrameH



MODEL	
FRAME H1	FRAME_H2
VFD2800C43A	VFD2800C43E
VFD3150C43A	VFD3150C43E
VFD3550C43A	VFD3550C43E

1403.0 1347.0

[55.24] [53.03]

1729.0 1702.0 [68.07] [67.0]

Н1

	VFD3150 VFD3550		VFD3150 VFD3550		
Frame	W	н	D	W1	W2

38.0 [1.5]

			_						111
H1	700.0 [27.56]	1435.0 [56.5]	398.0 [15.67]	630.0 [24.8]	290.0 [11.42]	-	-	-	ā
Н2	700.0 [27.56]	1745.0 [68.7]	404.0 [15.9]	630.0 [24.8]	500.0 [19.69]	630.0 [24.8]	760.0 [29.92]	800.0 [31.5]	
Frame	H1	H2	D1	D2	D3	D4	D5	D6	Ø

D2	D3	D4	D5	D6	Ø	Ø1	Ø2	Ø3
-	-	-	-	-	13.0 [0.51]	-	-	-
103.0 [4.06]	307.0 [12.09]	68.0 [2.68]	205.0 [8.07]	342.0 [13.46]	13.0 [0.51]	22.0 [0.87]	34.0 [1.34]	117.5 [4.63]

Unit : mm[inch]



Attentions

Standard Motors

Used with 400V Standard Motors
 It is recommended to add an AC output reactor
 when using with a 400V standard motor to prevent
 damage to motor insulation.

Torque Characteristics and Temperature Rise

When a standard motor is drive controlled, the motor temperature will be higher than with DOL operation.

Please reduce the motor output torque when operating at low speeds to compensate less cooling efficiency.

For continuous constant torque at low speeds, external forced motor cooling is recommended.

· Vibration

When the motor drives the machine, resonances may occur, including machine resonances. Abnormal vibration may occur when operating a 2-pole motor at 60Hz or higher.

Noise

When a standard motor is drive controlled, the motor noise will be higher than with DOL operation. To lower the noise, please increase the carrier frequency of the drive. The motor fan can be very noisy when the motor speed exceeds 60Hz.

Special Motors

· High-speed Motor

To ensure safety, please try the frequency setting with another motor before operating the high-speed motor at 120Hz or higher.

· Explosion-proof Motor

Please use a motor and drive that comply with explosion-proof requirements.

· Submersible Motor & Pump

The rated current is higher than that of a standard motor.

Please check before operation and select the capa

city of the AC motor drive carefully.
The motor temperature characteristics differ from a standard motor, please set the motor thermal time constant to a lower value.

Brake Motor

When the motor is equipped with a mechanical brake, the brake should be powered by the mains supply.

Damage may occur when the brake is powered by the drive output. Please DO NOT drive the motor with the brake engaged.

Gear Motor

In gearboxes or reduction gears, lubrication may be reduced if the motor continuously is operated at low speeds. Please DO NOT operate in this way.

· Synchronous Motor

These kind of motors need suitable software to control them. Please contact Delta for more information.

· Single-phase Motor

Single-phase motors are not suitable for being operated by an AC Motor Drive. Please use a 3-phase motor instead when necessary.

Environmental Conditions

· Installation Position

- The drive is suitable to be installed in a place with ambient temperature from -10 to 50°C.
- The surface temperature of the drive and brake resistor will rise under specific operation conditions. Therefore, please install the drive on materials that are noncombustible.
- Ensure that the installation place complies with the ambient conditions as stated in the manual.

Wiring

· Limit of Wiring Distance

For the remote operation, please use twist-shielding cable and the distance between the drive and control box should be less than 20m.

Maximum Motor Cable Length Too long motor cables may cause overheating

the drive or current peaks due to stray capacitance. Please ensure that the motor cable is less than

Please ensure that the motor cable is less than 30m. If the cable length can't be reduced, please lower

the carrier frequency or use an AC reactor.

· Choose the Right Cable

Please refer to current value to choose the right cable section with enough capacity or use recommended cables.

· Grounding

Please ground the drive completely by using the grounding terminal.

How to Choose the Drive Capacity

· Standard Motor

Please select the drive according to applicable motor rated current listed in the drive specification.

Please select the next higher power AC drive in case higher starting torque or quick acceleration/deceleration is needed.

· Special Motor

Please select the drive according to Rated current of the drive > rated current of the motor

Peripheral Equipment

Molded-Case Circuit Breakers (MCCB)

Please install the recommended MCCB or ELCB in the main circuit of the drive and make sure that the capacity of the breaker is equal to or lower than the recommended one.

Add a Magnetic Contactor(MC) in the Output Circuit

When a MC installed in the output circuit of the drive to switch the motor to commercial power or other purposes, please make sure that the drive and motor are completely stopped and remove the surge absorbers from the MC before switching it.

Add a Magnetic Contactor (MC) in the Input Circuit

Please only switch the MC ONCE per hour or it may damage the drive. Please use RUN/STOP signal to switch many times during motor operation.

Motor Protection

The thermal protection function of the drive can be used to protect the motor by setting the operation level and motor type (standard motor or variable motor). When using a high-speed motor or a water-cooled motor the thermal time constant should be set to a lower value.

When using a longer cable to connect the motor thermal relay to a motor, high-frequency currents may enter via the stray capacitance. It may result in malfunctioning of the relay as the real current is lower than the setting of thermal relay. Under this condition, please lower the carrier frequency or add an AC reactor to solve

· DO NOT Use Capacitors to Improve the Power Factor

Use a DC reactor to improve the power factor of the drive. Please DO NOT install power factor correction capacitors on the main circuit of the drive to prevent motor faults due to over current.

Do NOT Use Surge Absorber Please DO NOT install surge absorbers on t

Please DO NOT install surge absorbers on the output circuit of the drive.

· Lower the Noise

To ensure compliance with EMC regulations, usually a filter and shielded wiring is used to lower the noise.

Method Used to Reduce the Surge Current

Surge currents may occur in the phase-lead capacitor of the power system, causing an overvoltage when the drive is stopped or at low loads.

It is recommended to add a DC reactor to the drive.

Transportation and Storage

Please transport and store the drive in the place within environment specifications.

21