Filter selector

Motor Type: MAC800   Filter version: 1.0

Position filter

Fast

Slow

Soft   Hard

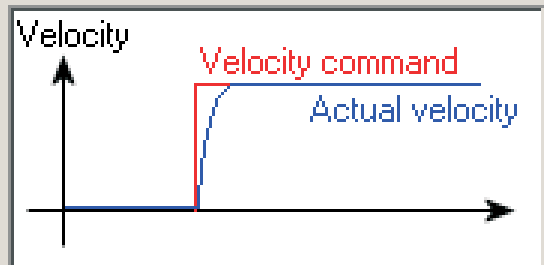Stability

More [gradient bar] Less

Hardness

Follow error

Torque applied to axis

Fastnes

Velocity

Velocity command

Actual velocity
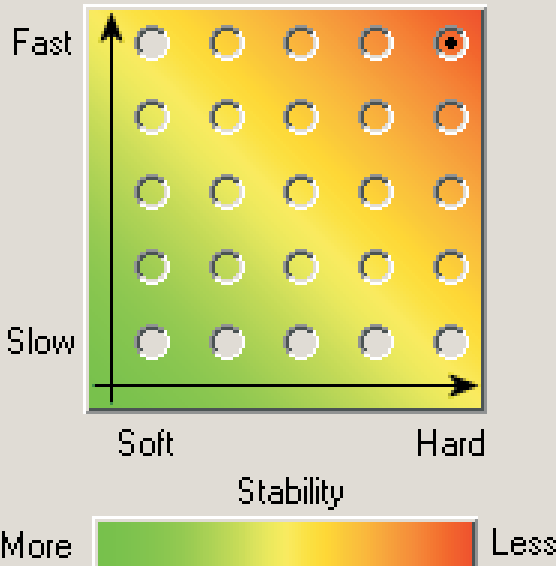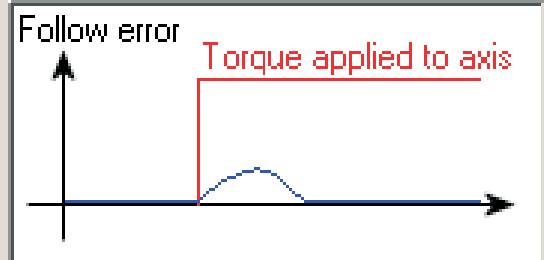
Damping

- ○ None
- ○ 96 Hz
- ○ 192 Hz
- ○ 385 Hz

Damping:
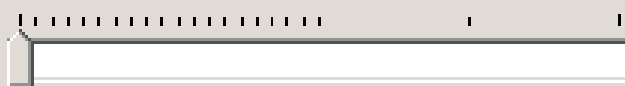The selected frequency will be supressed.
Use this feature if the system tends to oscillate.

Follow error compesation

Feed forward filter order

- ○ None ○ 1 ○ 2 ○ 3

Feed forward degree 0.0

Follow error compensation:
Can be used for minimizing the
follow error additionally
during a movement. Acceleration
and deceleration will
be sharper.

BMFxxxx

Load Filter   Close   Help <<