



Installation Guide for LinMot USB-CAN Converter for Configuration of E1100/B1100 Drives by CAN Bus

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CAN-USB Converter

Installation Guide

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1 Introduction

The USB-CAN converter can be used to login from a PC with installed LinMot-Talk software to one or more E1100/B1100 drives over the CAN bus. It can help the user to debug and configure the system in case the serial communication port is occupied (for example if the active interface is LinRS).



For E1100 drives, the MAC-ID is selected by the two rotary HEX switches S1 and S2.

For B1100 drive the MAC-ID is set via parameter. The default value is 63.

2 Technical Data

| | |
|----------------|---------------------------------|
| Unit: | USB interface |
| CPU: | Microprocessor Siemens SAB-C165 |
| Memory: | 256 Kbytes SRAM |
| CAN connector: | D-Sub 9 |
| PC connector: | USB connector |

2.1 CAN connector on USB-CAN Converter – Pin assignment

The USB – CAN converter is equipped with a D-Sub connector which provides connection to the CAN bus conforming to the CAN High Speed Bus (ISO 11898).

DSUB 9 male:

| Pin | Signal |
|-----|--|
| 1 | N.C. |
| 2 | CAN_L |
| 3 | GND |
| 4 | N.C. |
| 5 | Drain connected to connector shield (1M/10n to isolated GND) |
| 6 | GND |
| 7 | CAN_H |
| 8 | N.C. |
| 9 | N.C. |

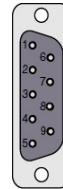
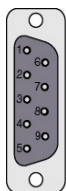


Table 2-1: Pinning of the CAN connector

2.2 CAN connector on LinMot Drive E1100 & B1100

2.2.1 Pin Description of the COM Connector:



DSBU 9 male:



| | | | |
|--------------|------------|--------------|--------------|
| Pin 1 | RS-485 TX+ | Pin 6 | RS-485 RX- |
| Pin 2 | RS-232 TX | Pin 7 | RS-485 TX- |
| Pin 3 | RS-232 RX | Pin 8 | CAN L |
| Pin 4 | RS-485 RX+ | Pin 9 | CAN H |
| Pin 5 | GND | | |

2.2.2 CAN Pin Description of the CMD and ME Connector:

2xRJ45 with 1:1 connected signals. Standard twisted pairs: 1/2, 3/6, 4/5, 7/8.
Ethernet cables according standard

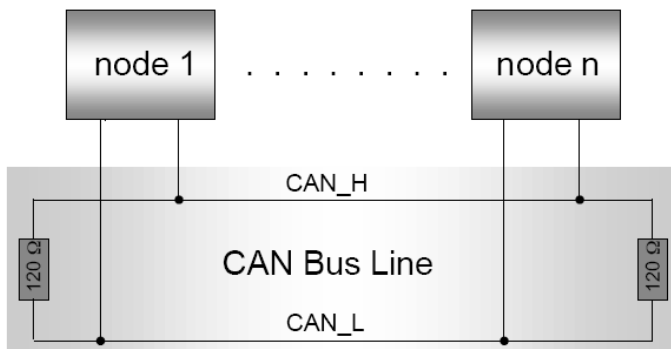
| | | | | |
|---|----------------------|--------------|---------------------|--------------|
|  | CMD Connector | | ME Connector | |
| | Pin 1 | RS485 A | Pin 1 | A |
| | Pin 2 | RS485 B | Pin 2 | /A |
| | Pin 3 | RS485 Y | Pin 3 | B |
| | Pin 4/5 | Ground | Pin 4 | Z |
| | Pin 6 | RS485 Z | Pin 5 | /Z |
| | Pin 7 | CAN H | Pin 6 | /B |
| | Pin 8 | CAN L | Pin 7 | CAN H |
|  | | | Pin 8 | CAN L |



On E1100-GP Drive use the ME connector, on E1100-DP, E1100-RS and B1100 drives use the CMD connector.


2.2.3 CAN Termination

The CANbus must be terminated by two 120 Ohm resistors at both ends of the bus line according the following scheme:



For easy installation, the LinMot CANopen drive has built in termination resistors, which can be activated if the LinMot drive is at the end of the bus line and if there is no termination in the connector.


S3
ON – OFF
RS485/232
RS485 Term
CAN Term
Interface



S3

E1100 drives: The built in termination resistor for the CAN bus can be activated by setting the dip switch “CAN Term” to “ON”
If the dip switch “Interface” is set to “OFF”, the CANopen Interface is deactivated.

S4
ON – OFF
RS485/232
RS485 Term
CAN Term
Interface



S4

B1100 drives: The built in termination resistor for the CAN bus can be activated by setting the dip switch “CAN Term” to “ON”
If the dip switch “Interface” is set to “OFF”, the CANopen Interface is deactivated.

3 How to install the USB-CAN converter

3.1 System Requirements

To run the USB-CAN interface converter your PC must meet the following requirements:

- 100% IBM-compatible
- At least one available USB port
- Windows XP/Vista/7

3.2 Installation

Note: Before connecting the USB-CAN converter to the PC, download and install the actual driver software from our home page:

<http://www.linmot.com/fileadmin/drivers/CANusb/Win32/CANDriversAndSoftware32.zip>
(drivers for Windows 32 bit OS)

<http://www.linmot.com/fileadmin/drivers/CANusb/Win64/CANDriversAndSoftware64.zip>
(driver for Windows 64 bit OS)

Unzip the downloaded file, run it to start the installation and follow the setup instruction as they appear).

After the driver has been installed successfully connect the USB-CAN converter to the PC and follow the proposed actions and settings.

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