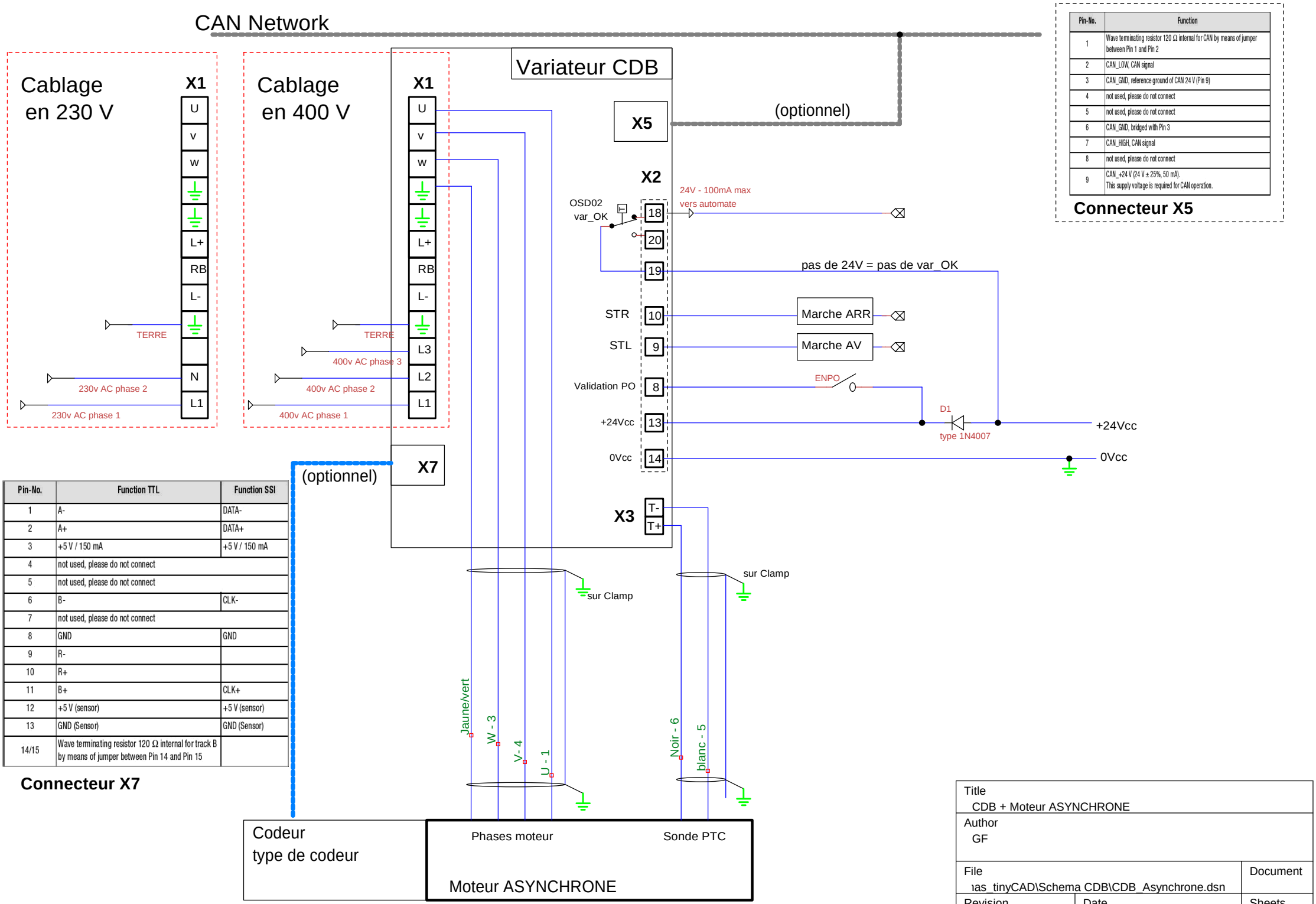

Pin-No.	Function
1	Wave terminating resistor 120 Ω internal for CAN by means of jumper between Pin 1 and Pin 2
2	CAN_LOW, CAN signal
3	CAN_GND, reference ground of CAN 24 V (Pin 9)
4	not used, please do not connect
5	not used, please do not connect
6	CAN_GND, bridged with Pin 3
7	CAN_HIGH, CAN signal
8	not used, please do not connect
9	CAN_+24 V (24 V ± 25%, 50 mA). This supply voltage is required for CAN operation.

Connecteur X5

Pin-No.	Function TTL	Function SSI
1	A-	DATA-
2	A+	DATA+
3	+5 V / 150 mA	+5 V / 150 mA
4	not used, please do not connect	
5	not used, please do not connect	
6	B-	CLK-
7	not used, please do not connect	
8	GND	GND
9	R-	
10	R+	
11	B+	CLK+
12	+5 V (sensor)	+5 V (sensor)
13	GND (Sensor)	GND (Sensor)
14/15	Wave terminating resistor 120 Ω internal for track B by means of jumper between Pin 14 and Pin 15	

Connecteur X7

Title: CDB + Moteur ASYNCHRONE		
Author: GF		
File: ıas_tinyCAD\Schema CDB\CDB_Asynchrone.dsn		Document
Revision: 1.2	Date: 2010-04-30	Sheets: 1 of 1