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# APPLICATION NOTE

### 1. Summary

There are some situations when the RS232 programming port of a Motion Coordinator does not connect to Motion Perfect.

This document is a step by step guide to checking the RS232 "command line" connection and establishing communication.

## 2. RS232 programming cable

The following tests must be done using the P350 RS232 serial cable supplied by Trio Motion Technology.

If a P350 cable is not available, it is possible to make a cable to the same specification using RS232 specification 3 core screened cable. The connectors must be wired as shown in figure 1.

#### Serial Cables

Trio recommend the use of their pre-made serial cables (product code P350). If cables need to be made to connect to a PC serial port the following connections are required:



Motion Coordinator to 'AT' style PC with 9pin serial connector

Figure 1. RS232 programming cable.

Test the cable with a known good Motion Coordinator before continuing.

### 3. Motion Perfect setup

Configure Motion Perfect with the correct serial port setting. Either "normal" or "fast" default setting should be used depending on the baud rate set in the Motion Coordinator. Menu: *Options-> Communications*. Click ADD button and set up the serial port.



Comunications Li	nk Configura	tion	23		
Link No: 2	] ;	Type: Serial 💌			
Port	COM5 👻				
Baud rate	Parity	Data bits			
9k6	C None	• 7			
C 19k2	C Odd	C 8			
C 38k4	Even	-Stop bits -			
C 115k2		0.1			
Use Packe	t Comms	© 2			
-Default confic	urations				
Normal (0600 7 e 2) East (38400 8 e 1)					
	OK	Cancel			

MC302X and MC302-k: use Fast default button.

MC2xx, OK and Status LEDs come on steady on power up: Use Normal default button.

MC2xx, OK and Status LEDs flash alternately on power up: Use Fast default button.

Figure 2. MP2 Baud rate setting

Open the Motion Perfect terminal in "Disconnected" mode. Menu: Tools->Terminal.



Figure 3. Motion Perfect in Disconnected Mode.



## 4. Test 1

- Connect only a power supply (24V dc) to the Motion Coordinator and remove all other connections to IO and motor drives.
- Begin the test with the 24V power OFF.
- Connect the serial cable between the Motion Coordinator port "Serial A" and the PC running Motion Perfect.
- Start Motion Perfect 2 as detailed in section 3.
- Switch on the 24V power to the Motion Coordinator.
- View the response in the Motion Perfect terminal.

Terminal: Serial:COM5:9600,7,e,2		Terminal: Serial:COM5:9600,7,e,2	_ 0 X
Terminal Edit Options		Terminal Edit Options	
Trio Motion Technology Ltd	*		*
		Total memory available: 401773	
MC Multitasking BASIC Version 1.67			
Created Nov 23 2011 @ 10:31:01		Compiling START	
		Linking START	
Axes initialised: 8		Pass=4	
		Compiling AR	
Servo axis : 0 1 2 3		Linking AR	
Servo 2 axis : None		Pass=4	
Stepper axis : None		Compiling MAIN	
Encoder axis : 4	=	Linking MAIN	
Stepper encoder axis : None	-	Pass=4	
Resolver axis : None		Compiling MANU	
Voltage output axis : None		Linking MANU	
Absolute serial axis : None		Pass=4	
Hardware Pswitch axis : None		Compiling COUPEVOL	
		Linking COUPEVOL	
CAN comms boards : None		Pass=4	
USB comms boards : 1		Compiling HOME	
SLM comms boards : None		Linking HOME	
SERCOS comms boards : None		Pass=4	
Profibus comms boards : None		Compiling COUPESUIVIE	
Ethernet comms boards : 0		Linking COUPESUIVIE	
Analog feedback boards : None		Pass=4	
Enhanced CAN boards : None		Compiling COUPEARRET	
EthernetIP comms boards: None		Linking COUPEARRET	
		Pass=4	
Feature enabled remote : 0		Compiling 2COUPESARRET	
		Linking 2COUPESARRET	
Input numbers: 0-15		Pass=4	E
Output numbers: 8-15		Compiling CONTROLE	
		Linking CONTROLE	
Processes initialised: 8		Pass=4	
		Compiling CHEN	
Test APPS RAM: Success		Linking CHEN	
Test System RAM: Success		Pass=4	
		>>%[Process 7:Program START] - Running	
EPROM selected for power up		<pre>%[Process 7:Line 261] (31) - Program is</pre>	stopped
FLASHSTICK allowed		<pre>%[Process 1:Program MAIN] - Running</pre>	
	•		*
	•	·	•
VT100 Log: Off	Serial:COM5:9600,7,e,2	VT100 Log: Off Ser	ial:COM5:9600,7,e,2

Figure 4. MC206X startup with no programs.

Figure 5. Startup showing programs auto-running

## 5. Diagnosis

#### 5.1. Is there Text in the Terminal?

If there is no text at all in the terminal, re-check the serial lead and Motion Perfect 2 operation with a known good Motion Coordinator.

If there is no text in the terminal and the cable is known to be OK, then the Motion Coordinator is



faulty and must be returned to Trio for repair.

If the text shown in Figure 4 appears, then the Motion Coordinator is working.

#### 5.2. Does the Return Key give a response?

If no programs are shown, then press the return key on the PC and check that the >> prompt is returned to the terminal.

Terminal: Serial:COM5:9600,7,e,2	
Terminal Edit Options	
Feature enabled remote : 0	~
Input numbers: 0-15	
Output numbers: 8-15	
Processes initialised: 8	
Test APPS RAM: Success Test System RAM: Success	
RAM selected for power up FLASHSTICK allowed	
Total memory available: 504537	
>>	_
>>	E
>>	
>>	Ψ.
·	P
VT100 Log: Off	Serial:COM5:9600,7,e,2

Figure 6. Response to pressing Return Key.

If there is no >> prompt, then either the input side of the RS232 connection is faulty or a program running on power up has changed the RS232 port setting.

#### 5.3. Are programs running?

If programs are shown compiling, linking and running, they may have changed the serial port setting.

Terminal: Serial:COM5:9600,7,e,2	l			X
Terminal Edit Options				
Compiling COUPEARRET				•
Linking COUPEARRET				
Pass=4				
Compiling 2COUPESARRET				
Linking 2COUPESARRET				
Pass=4				
Compiling CONTROLE				
Linking CONTROLE				
Pass=4				
Compiling CHEN				
Linking CHEN				
Pass=4				
>>%[Process 7:Program START] - Running	1			
<pre>%[Process 7:Line 261] (31) - Program i</pre>	is stop	pped	1	
<pre>%[Process 1:Program MAIN] - Running</pre>				
				-
>>HALT%[Process 1:Line				-
>> 287] (31) - Program is stopped				
				Ŧ
<				Þ.
VT100 Log: Off	Serial:CO	DM5:9	9600,7,e,	2 //.

Figure 7. Halting programs



If the >> prompt is available, type HALT <return>. See figure 7.

There are 2 possible reasons why you may not be able to type HALT.

- 1. A program has changed the RS232 port setting.
- 2. A running program is sending text to the terminal continuously.

In both cases first power down the Motion Coordinator, then power it up again and keep pressing the <return> key while the boot text arrives at the terminal. This will prevent the programs from starting. You will now be able to get the >> prompt.

### 6. Restoring the Motion Coordinator

If it is possible to get the >> prompt with Motion Perfect in "disconnected" mode, it should be possible to connect and synchronise the project.

Menu: Controller->Connect

Follow the process shown in the Motion Coordinator Technical Reference Manual to synchronise the project on the Motion Coordinator with your PC.

#### 6.1. Reasons for not connecting.

It may be that Motion Perfect still cannot connect to the Motion Coordinator. Reasons for this include:

#### 6.1.1. Project directory is corrupted.

Type DIR in the terminal. If the program names are mixed up and/or there are many \* in the manes and sizes, then the project is corrupted.

🕵 Terminal: Serial:C	OM5:9600,7,e,	2			) 23	ζ
Terminal Edit O	otions					
						*
<pre>%[Error 80] - Directory structure invalid</pre>						
>>						
DAM selected f	or nower 1					
Memory availab	le: 43407	5				
Selected progr	am: None	- -				
Directory is C	ORRUPT					
Program	Source	Code	Run Type	Code Type		
*TARTUP	1608	977	Manual	Normal		
MAIN	6492	3002	Auto( 5)	Normal		
TUNING	422	0	Manual	Normal		
DATUMING	1466	0	Manual	Normal		
INITIALISE	3282	826	Manual	Normal		
PLC	1388	0	Manual	Normal		
AUTOM	7293	3607	Manual	Normal		
MANUAL	688	463	Manual	Normal		
VR_DATA	18466	20482	Manual	Normal		
OK						E
>>						Ŧ
۰ III					•	
VT100 Log: Off			S	erial:COM5:960	0,7,e,2	1

Figure 8. Example of Corrupted Project

Solution 1 is to set the Motion Coordinator to restore the project from the EPROM. In the terminal type:

>>POWER\_UP=1 >>EX

The Motion Coordinator will power up and load the last project stored in EPROM, and if it is set to Autorun, it will try to run it.



Solution 2 is to clear the memory and then re-load from a backup on the PC. In the terminal type:

>>NEW ALL

There will now be no programs in the Motion Coordinator and it will be possible to connect Motion Perfect.

#### 6.1.2. Controller is LOCKed.

If the Motion Coordinator is locked with a LOCK code, it will not be possible to connect Motion Perfect.

g Terminal: Serial:CON	15:9600,7,e,	2			3
Terminal Edit Optio	ons				
>>dir EPROM selected for power up Memory available: 456460 Selected program: VR_DATA Directory is LOCKED					
Program	Source	Code	Run Type	Code Type	
STARTUP	1608	977	Manual	Normal	
MAIN	6492	0	Auto(5)	Normal	
TUNING	422	272	Manual	Normal	
DATUMING	1466	0	Manual	Normal	
INITIALISE	3282	826	Manual	Normal	
PLC	1388	827	Manual	Normal	
AUTOM	7293	3607	Manual	Normal	
MANUAL	688	463	Manual	Normal	
VR_DATA	18466	0	Manual	Normal	
OK					
>>					
I €					•
VT100 Log: Off			Se	rial:COM5:9600,7,e,2	1

Figure 9. Locked controller

Solution is to contact the machine builder and obtain the LOCK code, then type in the terminal:

>>UNLOCK(12345)

Replace 12345 with the lock code provided.

#### 6.1.3. Controller type is not in the Motion Perfect controller list.

Motion Perfect has a built-in list of all controllers which may be recognised. If the controller is a newer design than the version of Motion Perfect 2, then it will not be recognised and the "controller not found" message will be seen.

Solution is to download and install the latest version of Motion Perfect 2 from the Trio website at <a href="http://www.triomotion.com">www.triomotion.com</a>.

The latest version at the time of publishing this document is Motion Perfect V2.4.2.14. This version is good for all Motion Coordinator types in series 2 and 3 with an RS232 Serial programming port.

NOTE: Motion Coordinator Series 1, the CSC-DAC-MX, CSC-DAC-M and CSC-250-M cannot be used with Motion Perfect.