DRIVES FOR AUTOMATION

with the

Single-Axle Positioning System MC7000 PosMod

Application Information

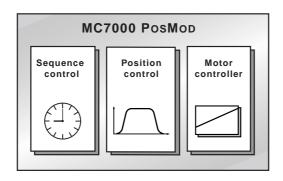




MC7000 PosMop - The Flexible Movement Solution

The MC7000 PosMod position controller combines the properties of a single-axle position and sequence control and a servocontroller in one unit. It controls the movement of the motor as well as simple NC sequences.

The Technology



Position control

- · Point-to-point positioning
- Floating set change without intermediate stop
- Linear and sine² shape ramps
- Indexing table function
- · electronic gearing
- superimposition of synchronous motion and positioning
- · two touch-probe inputs

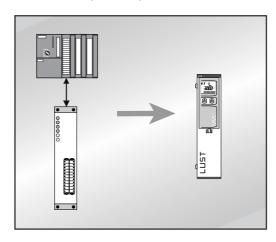
Sequence control

- · Processing of inputs and outputs
- Logic links
- Basic computing modes
- Comparative operations
- · Variables, flags, numerators and timers
- · Max. 700 program sets
- Set change in 5 ms

Motor controller

- Position, speed and torque controller
- Position controller with 0.25 ms cycle time
- Minimal lag error and maximum path accuracy

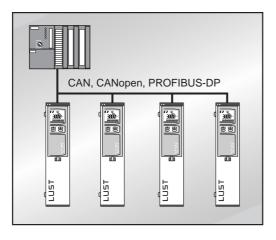
The Simplicity



The MC7000 PosMod contains two devices in one: a position and sequence control and a motor controller.

- You cut your costs, because positioning cards in the PLC are not needed.
- You avoid using the complete PLC for simple applications.
- You reduce your cabling.
- You save space in the cabinet.
- You increase the operational safety of your machine.

The Openness



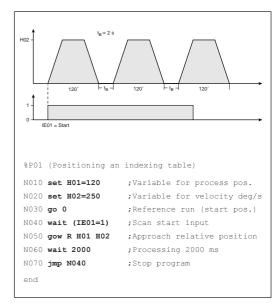
The MC7000 PosMod communicates as an intelligent subsystem via CAN, CANopen or PROFIBUS-DP with the programmable logic control or industrial PC.

- You have a simple means of transferring reference values, actual values and parameters and of controlling and monitoring the drive.
- You are provided with a simple means of integration in automation systems of a wide variety of manufacturers.
- You save wiring effort and commissioning time.

The Flexible Programmability

The flexible programmability of movements offers you the possibility of using the MC7000 PosMod for a wide variety of applications.

- You save time spent on induction, training and service.
- You cut your warehousing costs.
- You can change products simply at the press of a button and so
- Shorten your downtimes and
- Increase the productivity of your machine.



Movement profile of an indexing table and associated sequence program

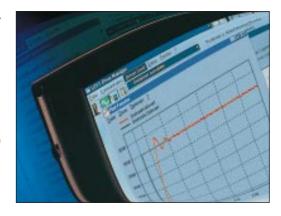
The Operation

DRIVEMANAGER user interface for programming and commissioning

• You reduce time spent on induction, training and service.

CP100 operator terminal for machine setup

 You can operate and control the MC7000 PosMod autonomously with no higherorder controller.



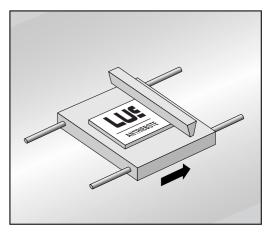
The Precision

The MC7000 PosMop delivers a positioning accuracy of ± 10' (with spindle pitch 5 mm, i = 1:10 → accuracy: ± 2 µm) with a resolver.

This low-cost encoder system alone makes the position controller a suitable solution for 90% of all applications.

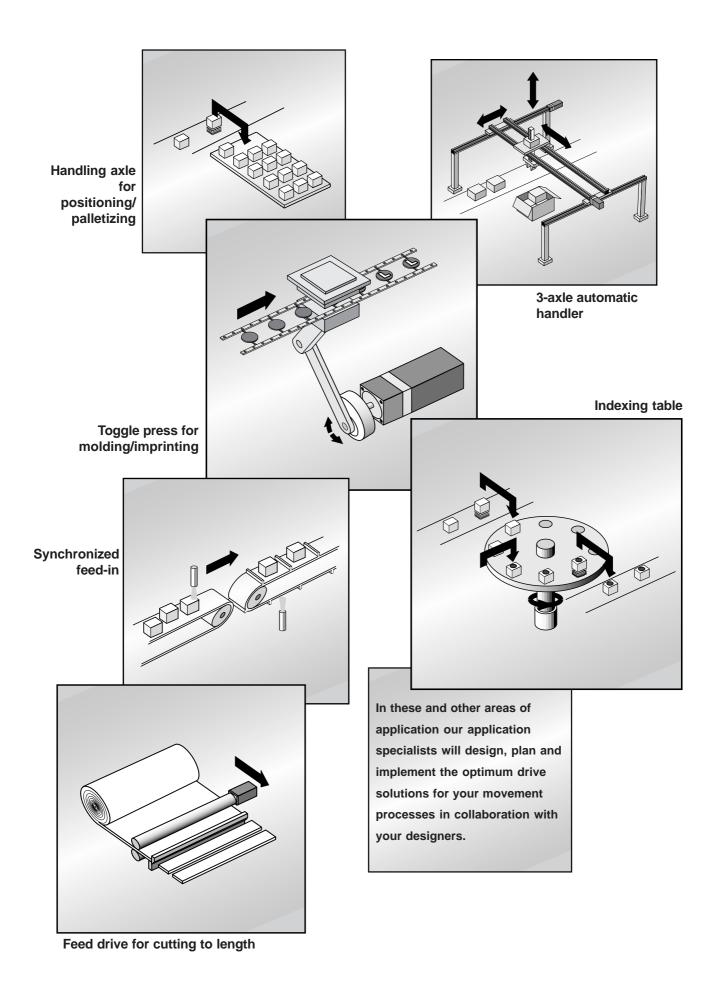
 With a sine-cosine encoder a positioning accuracy of < ± 0,5' is attainable (with spindle pitch 5 mm, i = 1:10 → accuracy: 0,1 µm).

With this encoder system the MC7000 PosMod can also be used for applications demanding ultra-high precision.



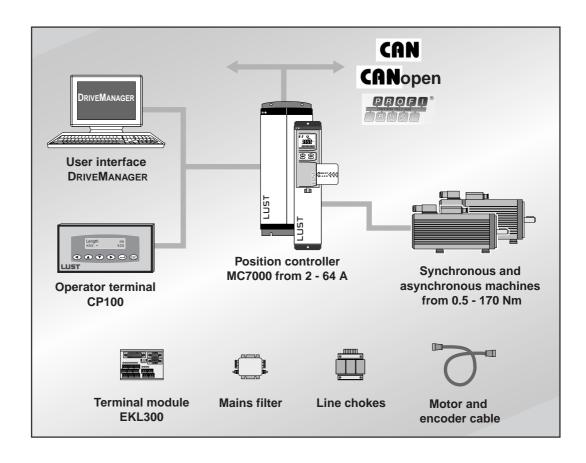
Exposure unit/scanner

Areas of Application

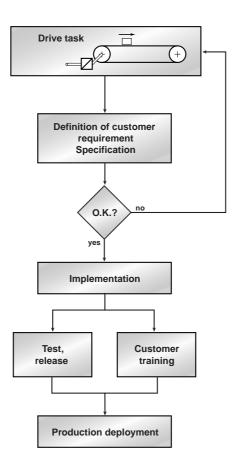


Our Solution Package

The System



Our Application Support



We would be pleased to plan and implement your first MC7000 PosMod project jointly with you.

On request we can provide you with assistance in

- ➤ Movement analysis
- ➤ Planning the drive system
- ➤ Writing sequence programs
- ➤ Tests and commissioning
- ➤ Training

After the first joint project you will find it easy to translate your own ideas into flexible movement solutions.

Selected Drive Packages

| | | <u> </u> | | | | | | | | |
|-------------------------|-------|--|----------------------------|---------------------------------------|--|---------------------------------------|------------------------|--|--|----------|
| | | Research the second sec | TEUST TEUST | 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 | STOO ON O | o o o o o o o o o o o o o o o o o o o | Acc. | oning the second | Se de la company | <u>%</u> |
| nstallation window [mm] | | Servomotor | Drive controller 2) | M _{max} [Nm] | n _N [rpm] | J _L [kgcm²] | t _B [ms] | | | |
| 55 | (O) | PSM-M4-20R86-4 | MC7402 MC7404 | 1.9 3.2 | 6000 | 0.45 | 15 9 | internal | DND 6 | |
| 70 | 0 | PSM-N4-20R84-4 | MC7402 | 2.4 | 4000 | 0.22 | 4 | internal | DND 6 | |
| | | PSM-N6-20R84-4 | MC7402 MC7404 | 4 8 | 4000 | 0.57 | 6 3 | internal internal | DND 6 DND 6 | |
| 92 | • | PSM-03-20R83-4 | MC7402 MC7404 | 6.1 9.2 | 3000 | 5.3 | 28 19 | internal internal | DND 6 | |
| | (000) | PSM-04-20R83-4 | MC7404 MC7408 | 10.3 16.4 | 3000 | 7.4 | 23 15 | internal NFD 10.3 | DND 6 DND 14 | |
|]110 | ••• | ASM-12-20R23-0 | MC7402 MC7404 | 3.8 6.8 | 3000 | 3.7 | 31 17 | internal internal | DND 6 | |
| | | PSM-13-20R83-4 | MC7404 MC7408 | 11.8 22.4 | 3000 | 11.7 | 32 17 | intern NFD 10.3 | DND 6 DND 14 | |
|]140 | ⊕• | ASM-22-20R23-0 | MC7404 MC7408 | 8.4 16.7 | 3000 | 14.4 | 26 17 | internal NFD 10.3 | DND 6 DND 14 | |
| | | PSM-23-20R83-0 | MC7408 MC7412 MC7416 | 24.5 36.8 44.8 | 3000 | 28 | 36 24 20 | NFD 10.3 NFD 25.1 NFD 25.1 | DND 14 DND 18 DND 24 | |
| | | ASM-25-20R22-0 | MC7408 MC7412 | 31.5 47.3 | 3000 | 38.4 | 26 17 | NFD 10.3 NFD 25.1 | DND 14 DND 18 | |
| 190 | | ASM-32-20R21-0 | MC7408 MC7412 MC7416 | 40 60 68 | 1500 | 90 | 36 24 21 | NFD 10.3 NFD 25.1 NFD 25.1 | DND 14 DND 18 DND 24 | |
| | | ASM-34-20R21-0 | MC7412 MC7416 MC7432 | 66.7 88.9 140 | 1500 | 209 | 50 37 24 | NFD 25.1 NFD 25.1 NFD 50.1 | DND 18 DND 24 DND 45 | |
| 260 | | ASM 43-20R21-0 | MC7432 MC7464 | 147.4 221.1 | 1500 | 960 | 103 69 | NFD 50.1 NFD 80.0 | DND 45 DND 75 | |

- 1) Acceleration with peak torque, no load, from standstill to nominal speed
- Speed-controlled applications: Electronic gearing, stepper motor mode: Single-axle positioning system:

Application package Basic Application package Motion Application package PosMod



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